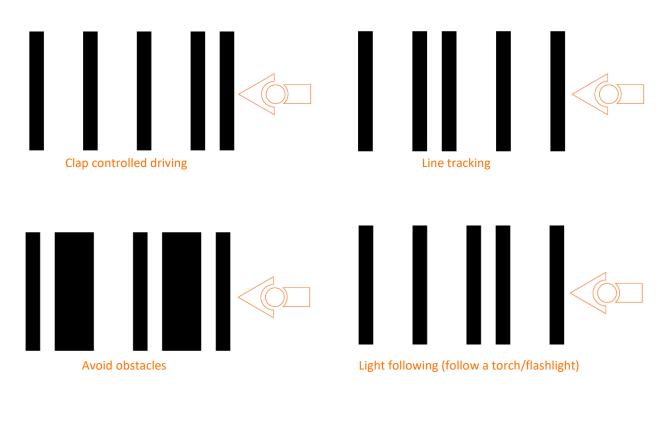
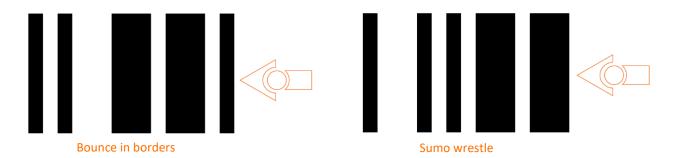


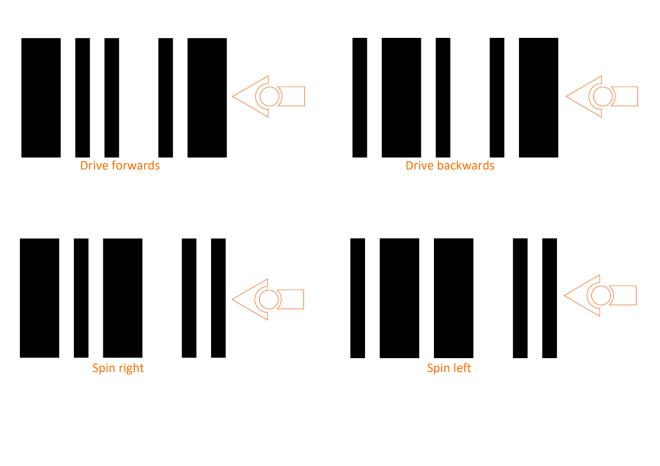
### Pre-set barcode programs for Edison

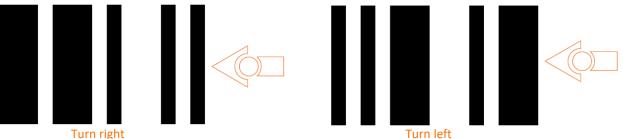


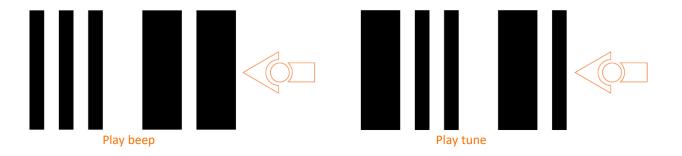




#### Remote control driving with Edison

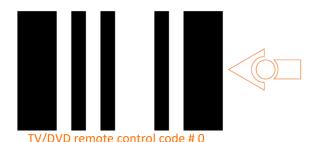


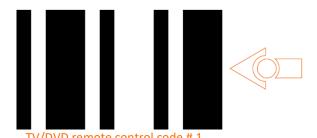


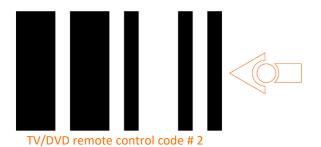


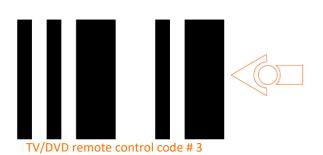


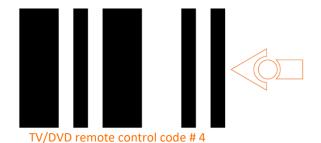
Remote control driving with Edison – programmable commands

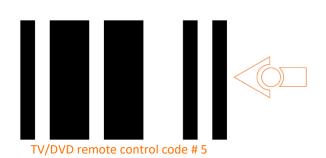


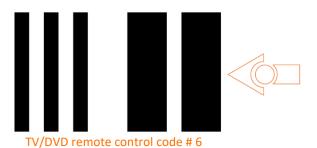


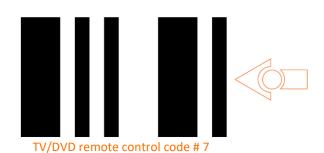






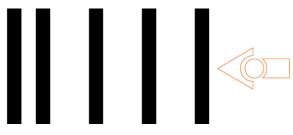








#### Calibration barcodes



Drive calibration – V2.0 robots only

#### **Drive calibration instructions**

- 1. Scan the barcode with a V2.0 Edison.
- 2. Press the play button twice.



Calibrate obstacle detection

#### **Obstacle detection calibration instructions**

#### Set maximum sensitivity:

- 1. Scan the barcode with Edison. Remove any obstacles in front of Edison.
- 2. Press the play button to enter calibration mode. The left sensitivity is calibrated first.
- 3. Repeatedly press the play button (this increases sensitivity) until the left red LED is flickering.
- 4. Repeatedly press the record (round) button (this decreases sensitivity) until the LED completely stops flickering.
- 5. Press the stop (square) button to switch to calibrate the right side.
- 6. Repeatedly press the play button until the right red LED is flickering. Now repeatedly press the record button until the LED completely stops flickering.
- 7. Press the stop button and the calibration is complete.

#### Set custom sensitivity:

You can set the distance that obstacles are detected by placing an obstacle in front of Edison and repeating above steps 1 through 7.